

# Liam Dugan

609-304-6690 | [ldugan@seas.upenn.edu](mailto:ldugan@seas.upenn.edu) | [linkedin.com/in/liam-dugan](https://www.linkedin.com/in/liam-dugan) | [liamdugan.com](http://liamdugan.com)

## EDUCATION

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UNIVERSITY OF PENNSYLVANIA Philadelphia, PA  
**M.S.E, Robotics (GPA: 3.80/4.00)** Aug. 2017 – Dec. 2020  
*Master's Thesis: Learning Formality from Japanese-English Parallel Corpora*

UNIVERSITY OF PENNSYLVANIA Philadelphia, PA  
**B.S.E, Computer Engineering & East Asian Studies (GPA: 3.63/4.00)** Aug. 2015 – Aug. 2020

DOSHISHA UNIVERSITY Kyoto, Japan  
**Kyoto Consortium of Japanese Studies (GPA: 3.70/4.00)** Jun. 2017 – Aug. 2017

## RESEARCH EXPERIENCE

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**Graduate Research Assistant** Jan. 2019 – Present  
*University of Pennsylvania Philadelphia, PA*

- Worked under Dr. Chris Callison-Burch in the NLP group at Penn:
- Developed a method for semi-supervised formality estimation using Japanese-English parallel corpora
- Developed a Web-Based annotation tool for evaluating the human detection of generated text
- Wrote a tool to project entities across machine translated articles for Arabic-English cross-lingual event extraction

## PUBLICATIONS

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### Referreed Conference Papers

1. Liam Dugan, Daphne Ippolito, Arun Kirubakaran, and Chris Callison-Burch. RoFT: A tool for evaluating human detection of machine-generated text. In *Proceedings of the 2020 Conference on Empirical Methods in Natural Language Processing: System Demonstrations*, pages 189–196, Online, October 2020. Association for Computational Linguistics
2. Zhengyi Luo, Austin Small, Liam Dugan, and Stephen Lane. Cloud chaser: real time deep learning computer vision on low computing power devices. *Eleventh International Conference on Machine Vision (ICMV 2018)*, Mar 2019

### In Submission

1. Liam Dugan and Chris Callison-Burch. Predicting english formality with japanese honorifics. In *Proceedings of the 2021 Annual Conference of the North American Chapter of the Association for Computational Linguistics*, Online, February 2021. Association for Computational Linguistics

### Other

1. Liam Dugan. Learning formality from japanese-english parallel corpora. Master's thesis, University of Pennsylvania, December 2020

## WORK EXPERIENCE

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**Autonomous Driving Software Intern** Jun. 2019 – Aug. 2019  
*NVIDIA Corporation Santa Clara, CA*

- Assisted development of a platform for on-demand downloads of self-driving car software
- Custom docker images are requested by engineers through a Jenkins server and images come pre-installed with latest software and can then be flashed onto vehicle hardware
- Service was deployed to over 500 developers on the NVIDIA DRIVE Team

## Software Engineering Intern

Jun. 2018 – Aug. 2018

*Robotic Research LLC*

*Clarksburg, MD*

- Worked on Velodyne VLP-16 LIDAR at the driver level for Autonomous Ground Resupply convoys
- Developed and prototyped novel object classifiers for sun speckles, dust, and vegetation
- Used a PCA-based volumetric analysis to tag neighboring points in a point cloud as possible vegetation or humans

## TEACHING EXPERIENCE

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### Teaching Assistant

- CIS530: Computational Linguistics – Fall 2020
- CIS530: Computational Linguistics – Spring 2020
- CIS380: Operating Systems **Head TA** – Fall 2019
- CIS548: Operating Systems Design and Implementation – Spring 2019
- CIS380: Operating Systems – Fall 2018
- CIS240: Introduction to Computer Systems – Spring 2018
- CIS240: Introduction to Computer Systems – Fall 2018
- CIS240: Introduction to Computer Systems – Spring 2017

### Lectures

- CIS380: Operating Systems “Linux Page Replacement Algorithms and Belady’s Anomaly” – Fall 2019

### Homework Assignments

- CIS530: Computational Linguistics “HW7: Transformers and State-of-the-Art Language Models” – Nov. 2020
- CIS530: Computational Linguistics “HW10: Neural Machine Translation” – Apr. 2020

## FELLOWSHIPS, AWARDS AND HONORS

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### Fellowships

- (October 2018) FLAS: Foreign Language and Area Studies Undergraduate Fellowship (East Asia) – \$15,000

### Certifications

- (May 2020) Penn Certificate of Japanese Proficiency
- (January 2018) Japanese Language Proficiency Test: N2

### Academic Honors

- (2017-2018) Dean’s List
- (2016-2017) Dean’s List

### Academic Awards

- (May 2020) Penn Engineering Exceptional Service Award
- (May 2020) Moore School Council Cwikla Award (Nominated)
- (May 2019) Penn Engineering Computer Science Senior Design Award Third Prize

### Hackathon Awards

- (February 2018) Most Innovative Use of Technology: WUFT Hacks
- (January 2018) Grand Prize: PennApps XVII
- (January 2018) Best use of Cloud Hosting: PennApps XVII
- (September 2017) Third Prize: PennApps XVI

## PRESENTATIONS, POSTERS AND TALKS

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### Posters

- “RoFT: A Tool for Evaluating Human Detection of Machine Generated Text” - Poster Presentation EMNLP 2020

### Presentations

- “Learning Formality from Japanese-English Parallel Corpora” - Live Presentation, Master’s Thesis ([video](#))
- “Scene++ VR” - Live Presentation, Penn Engineering Senior Design Demo Day ([video](#))
- “Cloud Chaser” - Live Presentation, PennApps XVII Closing Ceremony ([video](#))
- “Todd: The Inter-Dimensional Robot” - Live Presentation, PennApps XVI Closing Ceremony ([video](#))

## PROJECTS

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- SCENE++ VR | *Oculus Rift, ZED Mini, Unity 3D, Python, YOLOv3, Paperspace* May 2019
- **Won 3rd Prize in Penn Computer Science Senior Design Competition**
  - Hardware: Oculus Rift headset with head-mounted ZED mini depth camera for pass-through Augmented Reality
  - We introduce a cloud-based Unity API that allows VR Developers to query for objects around the user
  - We use Spatial Feature Mapping of environment to allow localization and stabilization of queried objects in depth
  - Use of cloud server allows Scene++ to run on any platform with *virtually no drop in FPS*
- RTX EXPLORE | *C++, DirectX Raytracing, NVIDIA TitanV* December 2018
- Built the first open-source path tracer in the DirectX Raytracing GPU framework (**40+ stars on GitHub**)
  - Features include: Dynamic model loading from .gltf and .obj, support for texture and normal maps, live editing of scene transformations through GUI interface, specular/refractive/dispersive/transmissive materials, subsurface scattering, anti-aliasing, depth of field
- BANKING WITH A VISION | *Python, Javascript, TCP, Bootstrap* February 2018
- **Won Most Innovative use of Technology at WUFT Hacks**
  - Use facial key-point mapping algorithm to perform face recognition through front facing webcam
  - Faces are used to access database of customer information to save bank tellers having to pull up user information
- CLOUD CHASER | *Python, C, TCP, AWS, YOLOv3, Alexa, Raspberry Pi, 3D Printing* January 2018
- **Won Grand Prize and Best use of Cloud Hosting at PennApps XVII**
  - Hardware: Raspberry Pi + camera, 3D printed robot chassis & camera mount, 4 servo motors, Amazon Echo Dot
  - Presented a platform that allows low resource IoT devices to do high level image processing on the cloud
  - Built robot “Chase” to demonstrate our platform. Commands are given to Chase through Echo Dot
  - Paper outlining our techniques to reduce latency of image streaming accepted to ICMV 2018
- TODD: THE INTER-DIMENSIONAL ROBOT | *C, HC-05 Bluetooth, Arduino, Unity 3D* September 2017
- **Won Third Prize at PennApps XVI**
  - Hardware: Arduino, breadboard, 2 servo motors, Bluetooth HC-05 controller
  - USB connected Bluetooth controller allows Unity to communicate with “Todd” the robot
  - Made multiplayer game where player controlling Todd has to dodge objects only visible in virtual world
- FIX YOURSELF | *C, Photon Microcontroller, Node.js, Heroku, Vibration Motor, Accelerometer* May 2017
- Introduced a low-power posture tracker device that attaches to a user’s back and vibrates when posture is off
  - Posture data is transmitted to a web server via WiFi so that users can track their posture over time
  - This idea would later be taken separately to market by startups such as Upright and Lumo Lift
- DOKUSHA | *Javascript, React, Express, Mongoose, Node.js* April 2017
- Dokusha is a full-stack web app that allows users to find appropriate reading material when studying languages
  - Users read books through the site interface and vocabulary profiles are made based off read material.
  - Once vocabulary profiles are made, books can be sorted by highest percentage of known words

## TECHNICAL SKILLS

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**Languages:** English (native), Japanese (advanced - 5+ years), Spanish (elementary - 2 years)  
**Programming Languages:** Python, C/C++, bash, CUDA, Java, JavaScript, Go, HTML/CSS, Verilog, MATLAB  
**Frameworks:** PyTorch, Tensorflow, OpenCV, DXR, Vulkan, OpenGL, WebGL, React, Node, Gatsby, Django  
**Developer Tools:** Git, Docker, Google Cloud Platform, VS Code, emacs, Atom, tmux

## REFERENCES

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**Boon Thau Loo**, RCA Professor of Computer Science  
Director - UPenn Distributed Systems Lab  
boonloo@seas.upenn.edu

**Chris Callison-Burch**, Associate Professor  
Natural Language Processing  
ccb@cis.upenn.edu